SH7262/SH7264 Group
USB Interrupt Transfer by the USB Function Controller

Summary
This application note describes the configuration to use the SH7262/SH7264 USB 2.0 host/function module as the USB function controller and transfer data to the USB host in interrupt transfer.

Target Device
SH7264 MCU (In this document, SH7262/SH7264 are described as "SH7264").

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1. Introduction

1.1 Specifications
Specifies the SH7264 MCU as the USB function to transfer data to the USB host in interrupt transfer.

1.2 Modules Used
- USB 2.0 Host/Function Module (USB module)
- Direct Memory Access Controller (DMAC)
- Interrupt controller (INTC)

1.3 Applicable Conditions

<table>
<thead>
<tr>
<th>MCU</th>
<th>SH7262/SH7264</th>
</tr>
</thead>
<tbody>
<tr>
<td>Operating Frequency</td>
<td>Internal clock: 144 MHz</td>
</tr>
<tr>
<td></td>
<td>Bus clock: 72 MHz</td>
</tr>
<tr>
<td></td>
<td>Peripheral clock: 36 MHz</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Integrated Development</th>
<th>Renesas Technology Corp.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Environment</td>
<td>High-performance Embedded Workshop Ver.4.07.00</td>
</tr>
<tr>
<td>C Compiler</td>
<td>Renesas Technology SuperH RISC engine Family</td>
</tr>
<tr>
<td></td>
<td>C/C++ compiler package Ver.9.03 Release 00</td>
</tr>
<tr>
<td>Compiler Options</td>
<td>Default setting in the High-performance Embedded Workshop</td>
</tr>
<tr>
<td></td>
<td>(-cpu=sh2afpu -fpu=single -object=&quot;$(CONFIGDIR)$(FILELEAF).obj&quot;</td>
</tr>
<tr>
<td></td>
<td>-debug -gbr=auto -chginpath -errorpath -global_volatile=0 -opt_range=all</td>
</tr>
<tr>
<td></td>
<td>-infinite_loop=0 -del_vacant_loop=0 -struct_alloc=1 -nologo)</td>
</tr>
</tbody>
</table>

1.4 Related Application Note
For more information, refer to the following application notes:
- SH7262/SH7264 Group Example of Initialization
- SH7262/SH7264 Group Implementing the USB Enumeration on the USB Function Controller
- SH7262/SH7264 Group USB Bulk Transfer by the USB Function Controller
- SH7262/SH7264 Group USB Isochronous Transfer by the USB Function Controller
2. Applications

This application uses the USB 2.0 host/function module (USB module) as the USB function to transfer data to the USB host in interrupt transfer.

2.1 Overview of USB Module

(1) Includes the USB host controller and function controller compliant to USB high-speed
   • Includes the USB host controller and function controller
   • USB host controller and function controller can be switched by setting registers
   • Includes the USB transceiver

(2) Reduced number of external pins and space-saving installation
   • Includes the D+ pull-up resistor (When operating as the function)
   • Includes the D+ and D− pull-down resistors (When operating as the host)
   • Includes the D+ and D− terminator (When operating at high-speed)
   • Includes the D+ and D− output resistor (When operating at full-speed)

(3) Supports all types of USB transfer
   • Control transfer
   • Bulk transfer
   • Interrupt transfer (High-bandwidth is not supported)
   • Isochronous transfer (High-bandwidth is not supported)

(4) Internal bus interface
   • Includes two channels of DMA interface

(5) Pipe configuration
   • Includes 8-KB buffer memory for USB communication
   • Up to 10 pipes can be specified (including the default control pipe)
   • Programmable pipe configuration
   • Any endpoint number can be assigned to pipes 1 to 9
   • Transfer conditions for pipes are as follows:
     — Pipe 0: Control pipe (Default control pipe: DCP), 64-byte fixed single buffer
     — Pipes 1 and 2: Bulk or isochronous pipe, continuous transfer mode, programmable buffer size
       (Double buffering can be specified up to 2 KB)
     — Pipes 3 to 5: Bulk pipe, continuous transfer mode, programmable buffer size
       (Double buffering can be specified up to 2 KB)
     — Pipes 6 to 9: Interrupt pipe, 64-byte fixed single buffer

(6) Features as the host controller
   • High-speed (480 Mbps), full-speed (12 Mbps), and low-speed (1.5 Mbps) supported
   • Communicates with multiple peripherals via a hub (tier 1)
   • Automatically responds to the reset handshake
   • Automatically schedules to transmit SOF, and packets
   • Specifies the interval on isochronous and interrupt transfers
(7) Features as the function controller
- High-speed (480 Mbps), and full-speed (12 Mbps) supported
- Automatically detects the high-speed or full-speed operation by replying to the reset handshake
- Manages stage on control transfer
- Manages the device state
- Automatically responds to the SET_ADDRESS request
- NAK response interrupt (NRDY)
- SOF Tracking and Recovery

(8) Other features
- Completes transfer by counting transactions
- Delays the BRDY interrupt event notification timing (BFRE)
- Automatically clears the buffer memory after reading data from the pipe specified by the DnFIFO (n = 0, 1) port (DCLRME)
- Specifies NAK to the response PID by the end of transfer (SHTNAK)
### 2.2 Interrupt Transfer

Interrupt transfer is used to transfer small quantity of data periodically, which is useful for transferring small data with bounded-latency. Typical applications which include interrupt transfer are keyboard and mouse.

Interrupt transfer includes the following features:

- Periodic transfer
- Unidirectional (Interrupt IN transfer or interrupt OUT transfer)
- Consists of three packets such as the token, data, and handshake
- Maximum packet size: 1 to 1024 bytes (for high-speed endpoints)\(^{(1)}\)
  1 to 64 bytes (for full-speed endpoints)

As the periodic transfer is preferentially executed when scheduling (micro) frames, its latency is guaranteed. However, the number of transactions per (micro) frame is restricted to 1\(^{(2)}\). Interrupt transfer detects and corrects an error, since it handles the handshake in each transaction.

**Notes:**
1. When using interrupt transfer with the SH7264 USB module, set its maximum packet size between 1 and 64 bytes in high-speed transfer.
2. As the High-Bandwidth endpoint supports up to three transactions, however, the SH7264 USB module does not support the High-Bandwidth.

Figure 1 shows the interrupt transfer image.

![Diagram of Interrupt Transfer](image)

**Figure 1 Interrupt Transfer Image**
Figure 2 shows the packet response pattern for interrupt IN transfer. Figure 3 shows the packet response pattern for interrupt OUT transfer.

### Table: PID bit setting and Respond with packets

<table>
<thead>
<tr>
<th>PID bit setting</th>
<th>Respond with packets</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>BUF (B’01)</strong></td>
<td>Host → IN token → Function</td>
</tr>
<tr>
<td></td>
<td>Data packet</td>
</tr>
<tr>
<td></td>
<td>ACK</td>
</tr>
<tr>
<td>The buffer memory includes data to transmit when receiving token</td>
<td></td>
</tr>
</tbody>
</table>

| **BUF (B’01)**        | Host → IN token → Function |
|                       | Data packet           |
|                       | NAK                   |
| The buffer memory does not include data to transmit when receiving token |

| **NAK (B’00)**        | Host → IN token → Function |
|                       | STALL                 |

| **STALL (B’10 or B’11)** | Host → IN token → Function |
|                          | STALL                 |

---

**Figure 2 Packet Response Pattern for Interrupt IN Transfer**

<table>
<thead>
<tr>
<th>PID bit setting</th>
<th>Respond with packets</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>BUF (B’01)</strong></td>
<td>Host → OUT token → Function</td>
</tr>
<tr>
<td></td>
<td>Data packet</td>
</tr>
<tr>
<td></td>
<td>ACK</td>
</tr>
<tr>
<td>The buffer memory includes available space when receiving token</td>
<td></td>
</tr>
</tbody>
</table>

| **BUF (B’01)**        | Host → OUT token → Function |
|                       | Data packet           |
|                       | NAK                   |
| The buffer memory is full when receiving token |

| **NAK (B’00)**        | Host → OUT token → Function |
|                       | NAK                   |

| **STALL (B’10 or B’11)** | Host → OUT token → Function |
|                          | STALL                 |

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**Figure 3 Packet Response Pattern for Interrupt OUT Transfer**
Figure 4 shows interrupt transfer setting procedures (overview).
For more information on how to initialize the pipe, refer to 2.3 Pipes. Refer to 2.4 FIFO Port for how to access FIFO port.

• Initializes the pipe according to the configuration specified by the Set Configuration request.

Set the PID bit to the BUF response

Write the transmit data to FIFO port

No (Interrupt OUT)

Initialize the pipe

Interrupt IN?

Yes

Yes

Set the PID bit to the BUF response

No

Reception completed?

Yes

End

Figure 4 Interrupt Transfer Setting Procedure (Overview)
2.3 Pipes

A USB pipe is a logic communication path in the USB transfer. Specify the transfer type and direction on every pipe to execute multiple USB transfers on a device.

2.3.1 Overview

Figure 5 shows an overview of the pipe.

A USB module uses 10 pipes including the default control pipe (DCP). Pipe 0 (DCP) supports control transfer only. Refer to the "SH7262/SH7264 Group Implementing the USB Enumeration on the USB Function Controller" for details on the DCP. Pipes 1 and 2 are for isochronous transfer, pipes 3 to 5 are for bulk transfer, and pipe 6 to 9 are for interrupt transfer. Note that pipes 1 and 2 can be used for bulk transfer. Pipes 1 to 5 are allowed for using the double buffering and transaction counter to transfer large amount of data. For setting pipes 1 to 9, see 2.3.2 Pipe Configuration Procedure.
USB bus interface

Pipe 0 (DCP)

Control transfer

DCPCFG  
DCPMAXP  
Configuration

Data

State

Control

DCPCTR

Pipe 1

Pipe 2

Pipe 3

Pipe 4

Pipe 5

Pipe 6

Pipe 7

Pipe 8

Pipe 9

Isochronous transfer (2)

Pipe 1 buffer

PIPE1CTR

PIPE1TRE

Pipe 2 buffer

PIPE2CTR

PIPE2TRE

Pipe 3 buffer

PIPE3CTR

PIPE3TRE

Pipe 4 buffer

PIPE4CTR

PIPE4TRE

Pipe 5 buffer

PIPE5CTR

PIPE5TRE

Pipe 6 buffer

PIPE6CTR

PIPE6TRE

Pipe 7 buffer

PIPE7CTR

PIPE7TRE

Pipe 8 buffer

PIPE8CTR

PIPE8TRE

Pipe 9 buffer

PIPE9CTR

Bulk transfer

Interrupt transfer

USB Host

Notes:
1. This register is used only in isochronous transfer.
2. Pipes 1 and 2 can be used as bulk pipe.

Figure 5 Pipes (Overview)
2.3.2 Pipe Configuration Procedure

Figure 6 shows the configuration procedure of pipes. For details on the pipe setting, refer to 2.3.3 Transmit Pipe Setting (Interrupt IN Transfer) and 2.3.4 Receive Pipe Setting (Interrupt OUT Transfer).

Pipes can be set dynamically. Normally, pipes are set when the target endpoint is decided. As pipes 1 to 9 use some of registers in common, set the target pipe by the Pipe window select register (PIPESEL) before configuration. Note that pipes cannot be configured when the target pipe is already allocated to the FIFO port, or when the PID bit setting is other than NAK.

![Pipe Configuration Diagram]

Figure 6 Pipe Configuration Procedure

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Note: If the PID bit is set to STALL (B’11), set it to STALL (B’10), and then reset it to NAK (B’00).
2.3.3 Transmit Pipe Setting (Interrupt IN Transfer)

This section describes an example of pipe setting when transferring data in interrupt IN transfer.

Table 1 lists the setting example of interrupt IN transfer using pipe 6. Figure 7 shows the operation example using the setting listed in Table 1. As double buffering and continuous transfer mode cannot be used in this example, use BEMP interrupt to write transactions one by one to FIFO buffer memory. For details, refer to (1) to (6) described in following pages.

Table 1 Interrupt IN Transfer Setting Example Using Pipe 6

<table>
<thead>
<tr>
<th>Register Name</th>
<th>Setting</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>PIPESEL register</td>
<td>H'0006</td>
<td>Set pipe 6 as the target pipe</td>
</tr>
<tr>
<td>PIPECFG register</td>
<td>H'8016</td>
<td>TYPE [1:0] bits = 2 Set the transfer type as interrupt transfer</td>
</tr>
<tr>
<td></td>
<td>BFRE bit = 0</td>
<td>BRDY interrupt when transmitting/receiving data</td>
</tr>
<tr>
<td></td>
<td>(This bit is not enabled in interrupt transfer)</td>
<td></td>
</tr>
<tr>
<td></td>
<td>DBLB bit = 0</td>
<td>Single buffering</td>
</tr>
<tr>
<td></td>
<td>(This bit is not enabled in interrupt transfer)</td>
<td></td>
</tr>
<tr>
<td></td>
<td>CNTMD bit = 0</td>
<td>Non-continuous transfer mode</td>
</tr>
<tr>
<td></td>
<td>(This bit is not enabled in interrupt transfer)</td>
<td></td>
</tr>
<tr>
<td></td>
<td>SHTNAK bit = 0</td>
<td>Continues the pipe when a transfer is completed</td>
</tr>
<tr>
<td></td>
<td>(Only 0 can be specified when transmitting data)</td>
<td></td>
</tr>
<tr>
<td></td>
<td>DIR bit = 1</td>
<td>Set the transfer direction as transmit</td>
</tr>
<tr>
<td>PIPEBUF register</td>
<td>H'0004</td>
<td>BUFSIZE [4:0] bits = B'00000 Set the buffer size as 64 bytes (fixed)</td>
</tr>
<tr>
<td></td>
<td>BUFNMB [6:0] bits = 4</td>
<td>Set the first block of a buffer as 4 (fixed)</td>
</tr>
<tr>
<td>PIPEMAXP register</td>
<td>H'0040</td>
<td>Set the maximum packet size as 64 bytes</td>
</tr>
<tr>
<td>PIPEPERI register</td>
<td>H'0000</td>
<td>IFIS bit = 0 (Only 0 can be specified in interrupt transfer)</td>
</tr>
<tr>
<td></td>
<td>IITV [2:0] bits = 0 (Only 0 can be specified in interrupt transfer)</td>
<td></td>
</tr>
<tr>
<td>BRDYENB register</td>
<td>PIPE6BRDYE bit = 0</td>
<td>BRDY interrupt is disabled</td>
</tr>
<tr>
<td>NRDYENB register</td>
<td>PIPE6NRDYE bit = 0</td>
<td>NRDY interrupt is disabled</td>
</tr>
<tr>
<td>BEMPENB register</td>
<td>PIPE6BEMPE bit = 1</td>
<td>BEMP interrupt is enabled</td>
</tr>
<tr>
<td>SOFCFG register</td>
<td>BRDYM bit = 0</td>
<td>Clearing the BRDY interrupt status automatically is disabled</td>
</tr>
</tbody>
</table>

Note: The USB module executes interrupt transfer according to the cycle controlled by the USB host. Specify the interval by the bInterval field in the endpoint descriptor.
Interrupt IN Transfer Example (Transmitting 128-byte data)

<table>
<thead>
<tr>
<th>PID bit</th>
<th>IN token</th>
<th>Interval (128 µs × 2^n)</th>
</tr>
</thead>
</table>
| NAK (B'00) | BUF (B'01) | |}

Reply to the host:

- NAK (B'00)
- BUF (B'01)

FIFO buffer:

- Write to buffer (64 bytes)

PIPE6BEMP bit:

Transmission completed

Figure 7 Interrupt IN Transfer Example

(1) Double buffering (DBLB bit)

Double buffering ensures an efficient transmission of large amounts of data. Buffer is operated either by the USB module or the CPU. When using single buffering, the USB module cannot access buffer while the CPU (or DMAC) accesses the buffer. While the CPU accesses the buffer, double buffering allows the USB module to access another buffer to execute the USB transfer efficiently.

Note: Double buffering cannot be used in interrupt transfer.

Figure 8 Double Buffering
(2) Continuous transfer mode (CNTMD bit)
Use the continuous transfer mode to transmit or receive multiple transactions continuously. In a single transfer, interrupts are generated when the size of the transmitted or received data reaches the maximum packet size. In a continuous transfer, however, data can be transferred without interrupts to CPU until the size of data reaches the buffer size allocated to each pipe. If the size of data is smaller than the buffer size, set the BVAL bit to 1 to transmit the data.
Note: Continuous transfer mode cannot be used in interrupt transfer.

(3) Endpoint Number (EPNUM bit)
Specify the same value as the value of the corresponding endpoint descriptor.

(4) Maximum packet size (PIPEMAXP register)
Specify between 1 and 64 bytes. Note that the USB defines the allowable maximum packet size to be between 1 to 1024 bytes for interrupt transfer, however the SH7264 USB module supports up to 64 bytes.

(5) Buffer size and the number of the first block in the buffer (PIPEBUF register)
Figure 10 shows the setting example of the buffer size and the block number. To use the pipe, allocate the area from the USB module internal FIFO buffer memory. Specify the first block number and the number of blocks in units of 64-byte blocks as the area. Specify the first block number in the BUFNMB bit, and the value of the number of blocks to allocate -1 in the BUFSIZE bit. As pipes 6 to 9 are allocated to blocks 4 to 7, respectively, other blocks cannot be used.
(6) Enabling interrupts (BRDYENB register, BEMPENB register)

Figure 11 shows the interrupt timing in transmission. As interrupt IN transfer allows the single buffering only, both BRDY and BEMP interrupts occur at the same time.

When the BRDYM bit is set to 0, the software clears the BRDY bit to 0.

Figure 11 Interrupt Timing in Transmission
2.3.4 Receive Pipe Setting (Interrupt OUT Transfer)

This section describes an example of pipe setting when receiving data in interrupt OUT transfer. Table 2 lists the setting example of interrupt OUT transfer using pipe 7. Figure 12 shows the operation example using the setting listed in Table 2. As double buffering and continuous transfer mode cannot be used in this example, use BRDY interrupt to read transactions one by one from FIFO buffer memory. For details, refer to (1) to (7) described in following pages.

Table 2 Interrupt OUT Transfer Setting Example Using Pipe 7

<table>
<thead>
<tr>
<th>Register Name</th>
<th>Setting</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>PIPESEL register</td>
<td>H'0007</td>
<td>Set pipe 7 as the target pipe</td>
</tr>
<tr>
<td>PIPESEL register</td>
<td>H'8007</td>
<td>Type [1:0] bits = 2 Set the transfer type as interrupt transfer</td>
</tr>
<tr>
<td></td>
<td></td>
<td>BFRE bit = 0 BRDY interrupt when writing and reading data is completed</td>
</tr>
<tr>
<td></td>
<td></td>
<td>(This bit is not enabled in interrupt transfer)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>DBLB bit = 0 Single buffering</td>
</tr>
<tr>
<td></td>
<td></td>
<td>(This bit is not enabled in interrupt transfer)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CNTMD bit = 0 Non-continuous transfer mode</td>
</tr>
<tr>
<td></td>
<td></td>
<td>(This bit is not enabled in interrupt transfer)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>SHTNAK bit = 0 Continues the pipe when a transfer is completed</td>
</tr>
<tr>
<td></td>
<td></td>
<td>(This bit is not enabled in interrupt transfer)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>DIR bit = 0 Set the transfer direction as receive</td>
</tr>
<tr>
<td>PIPECFG register</td>
<td>H'80007</td>
<td>EPNUM bit = 7 Set the endpoint number as 7</td>
</tr>
<tr>
<td>PIPEBUF register</td>
<td>H'0005</td>
<td>BUFSIZE [4:0] bits = B'00000 Specify the buffer size as 64 bytes</td>
</tr>
<tr>
<td></td>
<td></td>
<td>BUFNMB [6:0] bits = 5 Specify the first block of a buffer as 5</td>
</tr>
<tr>
<td>PIPEMAXP register</td>
<td>H'0040</td>
<td>Specify the maximum packet size as 64 bytes</td>
</tr>
<tr>
<td>PIPEPERI register</td>
<td>H'0000</td>
<td>IFIS bit = 0 (Only 0 can be specified in interrupt transfer)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>IITV [2:0] bits = 0 (Only 0 can be specified in interrupt transfer)</td>
</tr>
<tr>
<td>BRDYENB register</td>
<td>PIPE4BRDYE bit = 1</td>
<td>BRDY interrupt is enabled</td>
</tr>
<tr>
<td>NRDYENB register</td>
<td>PIPE4NRDYE bit = 0</td>
<td>NRDY interrupt is disabled</td>
</tr>
<tr>
<td>BEMPENB register</td>
<td>PIPE4BEMPE bit = 0</td>
<td>BEMP interrupt is disabled</td>
</tr>
<tr>
<td>SOFCFG register</td>
<td>BRDYM bit = 0</td>
<td>Clearing the BRDY interrupt status automatically is disabled</td>
</tr>
</tbody>
</table>

Note: The USB module executes interrupt transfer according to the cycle controlled by the USB host. Specify the interval by the bInterval field in the endpoint descriptor.
Interrupt OUT Transfer Example (Receiving 128-byte data)

(1) Disabling pipes when transfer is completed (SHTNAK bit)
When setting the SHTNAK bit to disable pipes when a transfer is completed, the USB module automatically changes the PID bit to NAK on receiving transfer is completed, which facilitates the transfer processing. When setting the SHTNAK of the receive pipe to 1, the USB module sets the PID bit corresponding to the target pipe to NAK. The USB module determines that the transfer is completed when the following conditions are satisfied. These functions can be used with pipes 1 to 5, receive pipes.
- When receiving the short packet data (including zero-length packet) correctly
- Using the transaction counter to receive packets of transaction counted correctly

Note: This setting (SHTNAK bit = 1) cannot be used in interrupt transfer.

(2) Enabling interrupts (BRDYENB register)
Figure 13 shows the interrupt timing in reception.

Figure 12 Interrupt OUT Transfer Example

Figure 13 Interrupt Timing in Reception
(3) Double buffering (DBLB bit)
   Apply the same setting as the transmission. See 2.3.3 for details.

(4) Continuous transfer mode (CNTMD bit)
   Apply the same setting as the transmission. See 2.3.3 for details.

(5) Maximum packet size (PIPEMAXP register)
   Apply the same setting as the transmission. See 2.3.3 for details.

(6) Endpoint number (EPNUM bit)
   Apply the same setting as the transmission. See 2.3.3 for details.

(7) Buffer size and the number of the first block in the buffer
   Apply the same setting as the transmission. See 2.3.3 for details.
2.4 FIFO Port

Use FIFO port to access (read or write data) the FIFO buffer memory allocated to pipes. This section describes how to access the FIFO buffer memory.

2.4.1 FIFO Port Overview

Figure 14 shows an overview of the FIFO port. The FIFO port has three registers (C/DnFIFO port registers). Specify the pipe number in the CURPIPE bit in the C/DnFIFOSEL register to access the FIFO buffer memory allocated to the specified pipe via the C/DnFIFO port register. Specify the access bit width and endianness in the C/DnFIFOSEL register. The C/DnFIFOCTR register indicates the write end in the buffer memory, and clears buffer.

Make sure to check the setting in the FRDY bit in the C/DnFIFOCTR register before accessing the C/DnFIFO port register, since the FIFO buffer memory may be operated by the system (CPU) or by the USB module (SIE). See bits BSTS and INBUFM in the DCPCTR register and the PIPEnCTR register to check the buffer status in each pipe.

The DCP buffer can be allocated only to the CFIFO port register. The DMA transfer can be used in the D0FIFO port register and the D1FIFO port register.

![Figure 14 FIFO Port (Overview)](image-url)
2.4.2 Writing Data to the FIFO Port (Interrupt IN Transfer)

The DnFIFO port register can be used to execute the DMA transfer in Interrupt IN transfer, however, this section describes the procedures on writing data to the CFIFO port register using the CPU transfer.

Figure 15, Figure 16, and Figure 17 show flow charts of writing data to FIFO port.

As the CFIFOSEL register is also used by the default control pipe, the register value may be rewritten depending on the interrupt used by control transfer. When rewriting the CFIFOSEL register by the interrupt, write back the value as appropriate.

---

**Figure 15 Writing Data to the FIFO Port**

- **Yes**
  - When the PID bit in the PIPEnCTR register is set to STALL (B'10) or STALL (B'11) as a bad response, transfer is canceled.

- **No**
  - Calculate the access width by the address and the size of data to write, whether in long words or words

- **Yes**
  - Set the CFIFOSEL register
    - Functions:
      1. The buffer point is not rewound
      2. Specify the access width
      3. Specify the byte order
      4. Specify the target pipe
    - (ISEL bit is not enabled when the DCP is not selected)

- **No**
  - Retrieve the access width

- **Yes**
  - Set the FIFO port select register (CFIFOSEL)

- **No**
  - Write 1 Transfer data to the CFIFO port

---

**Note:** Set bits other than the target bit to 1.
Figure 16 Writing 1 Transaction Data to CFIFO Port

- Set the FIFO port select register (CFIFOSEL)
- Write the value calculated at the transmission start to the CFIFOSEL register
- After switching the CURPIPE bit, wait until the written value matches the read value
- Wait until the FRDY bit in the CFIFOCTR register is set to 1, and then access the FIFO port
- Set the either smaller value of the remaining data size or maximum packet size to the variable as the transfer size
- When the transfer size is smaller than the maximum packet size, the data is not transmitted automatically
- Set the BVAL bit to 1 to start transmission
- Subtract the transfer size from the variable storing the remaining transfer data size
- Clear the buffer (BCLR bit = 1)

Figure 17 BEMP Interrupt Example

- BEMP interrupt
- Clear the BEMP interrupt status in the target pipe
- Clear the target bit in the BEMPSTS register to 0 (see note)
- Execute dummy read for three times to make sure to clear the interrupt status. See "7.10 Usage Note" in the SH7262, SH7264 Group, Hardware manual for details.
- Writing all data completed?
- Yes
- Disable BEMP interrupts
- No
- End
- Update the remaining data size

Note: Set bits other than the target bit to 1.
2.4.3 Reading Data from the FIFO Port (Interrupt OUT Transfer)

The DnFIFO port register can be used to execute the DMA transfer in Interrupt OUT transfer, however, this section describes the procedures on reading data from the CFIFO port register using the CPU transfer.

Figure 18 shows an example of reading data from FIFO port. Figure 19 shows an example of the BRDY interrupt.

As the CFIFOSEL register is also used by the default control pipe, like interrupt OUT transfer, the register value may be rewritten depending on the interrupt used by control transfer. When rewriting the CFIFOSEL register by the interrupt, write back the value as appropriate.

---

**Diagram:**

```
Reading data from the CFIFO port using the CPU transfer

PID = STALL?
  Yes
    • When the PID bit in the PIPEnCTR register is set to STALL (B'10) or STALL (B'11) as a bad response, transfer is cancelled.

  No
    • Clear the BRDY interrupt in the INTENB0 register to 0 to control the BRDYENB register exclusively

  End

  Clear the BRDY interrupt status in the target pipe

  Disable the BRDY interrupt

  Clear the BRDY interrupt status in the target pipe

  Dummy read for three times

  Enable the BRDY interrupt in the target pipe

  Enable the BRDY interrupt

  Set the response to the PID bit in the target pipe to BUF

  End

  Note: Set bits other than the target bit to 1.
```

---

**Figure 18 Reading Data from the FIFO Port**
BRDY interrupt

- Clear the BRDY interrupt status in the target pipe
- Dummy read for three times
- Retrieve the receive data size
- Retrieve the access size
- Unallocate the pipe from FIFO port (temporary)

Set the FIFO port select register (CFIFOSEL)

- Written value matches the read value?

No
- Written value matches the read value?

Yes
- Set the FIFO port select register (CFIFOSEL)
- Ready to access?

Yes
- Receive data size = Remaining size?

No (Overflow)
- Read the receive data size data from the CFIFO port register
- Update the remaining data size
- Receive data size = 0?

No
- Clear the buffer
- All data received?

No
- Disable the BRDY interrupt in the target pipe

End

Yes
- Set the STALL response (B'11)
- Clear the buffer
- Set the BCLR bit in the CFIFOCTR register to 1
- Disable the BRDY interrupt
- When receiving zero-length packet, clear the buffer. Set the BCLR bit in the CFIFOCTR register to 1.

Note: Set bits other than the target bit to 1.

Figure 19 BRDY Interrupt
3. References

- Software Manual
  SH-2A/SH-2A-FPU Software Manual Rev. 3.00
  The latest version of the software manual can be downloaded from the Renesas website.

- Hardware Manual
  SH7262 Group, SH7264 Group Hardware Manual Rev. 2.00
  The latest version of the hardware manual can be downloaded from the Renesas website.

- USB 2.0 Specifications
  Universal Serial Bus Specification Revision 2.00
  (http://www.usb.org/developers)
Website and Support

Renesas Technology Website
http://www.renesas.com/

Inquiries
http://www.renesas.com/inquiry
csc@renesas.com

Revision History

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